



PROTECTION RELAYS

FMR-M (FMR-X-PL)

Feeder manager relay with motor protection functions

Three-phase Current, Voltage and Earth Fault multifunction relay for protection and management of MV/HV distribution lines. Real time measurement of the primary value of the input quantities are continuously available from relay's display and from the serial communication port.

Relay's programming and setting can be made directly by the front face keyboard or via the serial communication ports. Setting, event recording and oscillography are stored into non volatile memory (E2prom).

The relay is fitted with a multivoltage, autoranging power supply unit self protected and transformer isolated. Besides the normal Watchdog and Powerfail functions, a comprehensive program of self-test and self-diagnostic provides:

- Diagnostic and functional test with checking of program routines and memory contents, running every time the auxiliary power supply is switched on.
- Dynamic functional test running during continuously normal operation.
- Complete Test (including or not including output relays) activated by the keyboard or via the communication bus.

Any internal fault detected is indicated by a fault message on the display and by deenergization of associated I.R.F. output relay.

The technical specifications reported are not binding and they should be agreed in the related contract.



MICROELETTRICA

Protective Functions

- F49 : One Thermal Image element
- F50/51/67 : Three levels for phase overcurrent independently programmable as directional or non directional
- F50N/51N/67N : Three levels for Earth Fault independently programmable as directional or non directional
- F27/59 : Two over/under voltage levels
- F81 : Two over/under frequency levels
- F46 : Two Negative Sequence current levels
- F59Uo : Zero sequence overvoltage level
- F51BF : Breaker Failure protection
- F27U1 : One Positive Sequence overvoltage level
- F59U2/47 : One Negative Sequence undervoltage level
- Two Reactive Power (VAR) control levels (optional)
- Two complete setting programs switchable locally or remotely
- F51LR : Locked Rotor
- F66 : Limitation of N° of Starting
- F37: No-Load Running
- Starting Sequence Control
- Motor Starts

Recording

- Event Recording (last 100 events)
- Trip Recording (last 20 trips) complete with cause of tripping and values of the input quantities at the moment of trip
- Oscillographic recording of input quantities (8 channels, 32 sample/cycle, 3 sec each)

Control

- 6 Output Relays user programmable
- 4 Digital Inputs user programmable
- Blocking input and Blocking output for pilot wire selectivity coordination
- Time tagging resolution 1ms.
- Trip circuit supervision
- Associated Circuit Breaker control (OPEN / CLOSE)
- Breaker interruption energy $\sum i^2 t$
- Complete autodiagnostic program with dedicated relay

Technical Characteristics

- Graphical Display (128x64 dot)
- 4 Leds for signalization
- Multilanguage Display (English/Italian standard, available - other on request)

Power Supply Ratings

- Autoranging multivoltage power supply
- Type 1 : 24V(-20%) / 110V(+15%) a.c. - 24V(-20%) / 125V(+20%) d.c.
- Type 2 : 80V(-20%) / 220V(+15%) a.c. - 90V(-20%) / 250V(+20%) d.c.

Communications

- 1 RS485 Serial communication port on rear side
- 1 RS232 Serial communication port on front panel
- Modbus RTU / IEC870-5-103 Communication Protocols
- Canbus port for external additional modules

Expansion Modules (optional)

- "UX10-4" 10 Digital Inputs and 4 Output Relays
- "14DI" 14 Digital Inputs
- "14DO" 14 Output Relays

Execution

- 2 Module box. (3 modules with 1 expansion, 4 modules with 2 expansion)
- IP44 protection case (on request IP54).
- Totally draw-out execution.

Software

- MCom2 Program interface for device management

Real Time Measurements

- la = current of phase A
- lb = current of phase B
- lc = current of phase C
- lo = neutral current
- Va = Voltage of phase A
- Vb = Voltage of phase B
- Vc = Voltage of phase C
- cosφ = Power Factor A,B,C
- Pa, Qa = Active, Reactive Power of phase A
- Pb, Qb = Active, Reactive Power of phase B
- Pc, Qc = Active, Reactive Power of phase C
- P, Q = Average of Active, Reactive Power
- +Wh,+Rh = Active, Reactive Exported Energy
- Wh,-Rh = Active, Reactive Imported Energy

F49 (T>): Thermal Image element with prealarm

Function enabling	ON - OFF	
Operation Mode	Opmod = (I1 - I2 / Imax)	
Temperature prealarm	Tal = (10 - 100)%Tn	step 1 %Tn
Setting range	Is = (0.5 - 1.5),	step 0.01
Time constant	Kt = (1 - 600)min	step 0.01min

1F - 67/50/51 (1I>): 1st Overcurrent Element

Function enabling	ON - OFF	
Time current curves	f(t) = Indep.Definite Time (D), IEC (A/B/C), IEEE (MI/VI/I/EI/SI)	
Operation Mode	f(a) = Non Directional - Directional Supervision - Total Directional	
Voltage restraint	f(U) = ON - OFF	
Current setting range	Is = (0.1 - 40) In	step 0.01In
Characteristic sensitivity direction	a = (0 - 359)°	step 1°
Instantaneous output	= ≤ 0.03s	
Independent time delay	ts = (0.02 ÷ 100)s	step 0.01s

2F & 3F - 67/50/51 (2I> & 3I>): 2nd & 3rd Overcurrent Elements - Individually Programmable

Function enabling	ON - OFF	
Operation Mode	f(a) = Non Directional - Directional Supervision - Total Directional	
Voltage restraint	f(U) = ON - OFF	
Current setting range	Is = (0.1 - 40) In	step 0.01In
Characteristic sensitivity direction	a = (0 - 359)°	step 1°
Instantaneous output	= ≤ 0.03s	
Independent time delay	ts = (0.02 ÷ 100)s	step 0.01s

Stabilization on Inrush current

Automatic doubling of the operation levels I>> and/or IH	2xI> = ON/OFF	
Activation level	di/dt = ≥25 In/s	
Revert level	I < 1.25In	

1F - 67N/50N/51N (1Io>): 1st Earth Fault Element

Function enabling	ON - OFF	
Operation Mode	f(ao) = Non Directional - Total Directional	
Time current curves	f(t) = Indep.Definite Time (D), IEC (A/B/C), IEEE (MI/VI/I/EI/SI)	
Current setting range	Is = (0.01 ÷ 4)On	step 0.01On
Minimum level of residual voltage for directional element	Vo = (0 ÷ 20)%Un	step 0.1%Un
Characteristic sensitivity direction	ao = (0 ÷ 359)°	step 1°
Trip sector amplitude	az = (0 ÷ 359)°	step 1°
Instantaneous output	0.03s	
Independent time delay	ts = (0.02 ÷ 100)s	step 0.01s

2F & 3F - 67N/50N/51N (2Io> & 3Io>): 2nd & 3rd Earth Fault Elements - Individually programmable

Function enabling	ON - OFF	
Operation Mode	f(ao) = Non Directional - Total Directional	
Characteristic sensitivity direction	ao = (0 ÷ 359)°	step 1°
Trip sector amplitude	az = (0 ÷ 359)°	step 1°
Current setting range	Is = (0.001 ÷ 0.20)On	step 0.001On
Instantaneous output	≤0.03s	
Independent time delay	ts = (0.02 ÷ 100)s	step 0.01s

1F - 46 (1Is>): 1st Negative Zero Sequence Element		
Function enabling	ON - OFF	
Time current curves	$f(t) = \text{Indep. Definite Time (D), IEC (A/B/C), IEEE (MI/VI/I/EI/SI)}$	
Setting range	$I_s = (0.1 \div 4)I_n$	step 0.01I _n
Instantaneous output	$\leq 0.03s$	
Independent time delay	$t_s = (0.02 \div 100)s$	step 0.01s
2F - 46 (2Is>): 2nd Negative Zero Sequence Element		
Function enabling	ON - OFF	
Setting range	$I_s = (0.1 \div 4)I_n$	step 0.01I _n
Instantaneous output	$\leq 0.03s$	
Independent time delay	$(0.02 \div 100)s$	step 0.01s
1F & 2F - 59 (1U> & 2U>): 1st & 2nd Maximum Voltage Elements - Individually programmable		
Function enabling	ON - OFF	
Setting range	$U_s = (10 \div 190)\%U_n$	step 0.01U _n
Instantaneous output	$\leq 0.03s$	
Independent time delay	$t_s = (0.02 \div 100)s$	step 0.01s
1F & 2F - 27 (1U< & 2U<): 1st & 2nd Minimum Voltage Elements - Individually programmable		
Function enabling	ON - OFF	
Setting range	$U_s = (10 \div 190)\%U_n$	step 0.01U _n
Instantaneous output	$\leq 0.03s$	
Independent time delay	$t_s = (0.02 \div 100)s$	step 0.01s
1F & 2F - 81> (1f> & 2f>): 1st & 2nd Maximum Frequency Elements - Individually programmable		
Function enabling	ON - OFF	
Setting range	$f_s = (40 \div 70)Hz$	step 0.01Hz
Instantaneous output	$\leq 0.03s$	
Independent time delay	$t_s = (0.02 \div 1000)s$	step 0.01s
1F & 2F - 81< (1f< & 2f<): 1st & 2nd Minimum Frequency Elements - Individually programmable		
Function enabling	ON - OFF	
Setting range	$f_s = (40 \div 70)Hz$	step 0.01Hz
Instantaneous output	$\leq 0.03s$	
Independent time delay	$t_s = (0.02 \div 1000)s$	step 0.01s
1F & 2F - 59U₀ (1U₀> & 2U₀>): 1st & 2nd Maximum Zero Sequence Overvoltage Elements - Individually programmable		
Function enabling	ON - OFF	
Setting range	$U_s = (1 \div 100)\%U_n$	step 0.01U _n
Instantaneous output	$\leq 0.03s$	
Independent time delay	$t_s = (0.02 \div 100)s$	step 0.01s
1F - 27U1 (U1<): Positive Sequence Undervoltage Element		
Function enabling	ON - OFF	
Setting range	$U_s = (10 \div 190)\%U_n$	step 1%U _n
Instantaneous output	$\leq 0.03s$	
Independent time delay	$t_s = (0.02 \div 100)s$	step 0.01s
1F - 59U2/47 (U2>): Negative Sequence Overvoltage Element		
Function enabling	ON - OFF	
Setting range	$U_s = (10 \div 190)\%U_n$	step 1%U _n
Instantaneous output	$\leq 0.03s$	
Independent time delay	$t_s = (0.02 \div 100)s$	step 0.01s

1F - (Wi): Circuit Breaker Energy Maintenance

Function enabling	ON - OFF	
Conventional interruption current	$I_i = (0.1 \div 99)I_n$	step 0.1In
Max Energy before maintenance	$W_i = (1 \div 9990)$	step 1

Breaker Failure Element

Alarm time delay	$t_{BF} = (0.05 \div 0.75)s$	step 0.01s
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Trip Circuit Supervision Element

Function enabling	ON - OFF	
Independent time delay	$t_s = (0.1 \div 100)s$	step 0.01s
Trip circuit voltage	$(24 \div 250)V_{dc}$	

F51LR - (ILR) Locked Rotor

Function enabling	ON - OFF	
Independent time delay	$ILR = (1 \div 5) I_n$	step 0.1In
Trip circuit voltage	$t_{LR} = (1 \div 120)s$	step 1

F66 (StNo) - Limitation of N° of Startings

Function enabling	ON - OFF	
Numbers of startings	$N_o = (1 \div 60)$,	step 1
Time interval for counting of StNo	$t_{No} = (60 \div 3600)s$	step 1s
Reset time after trip	$t_{Bst} = (60 \div 3600)s$	step 1s.

F37 - (I<) No-Load Running

Function enabling	ON - OFF	
Numbers of startings	$I_{<} = (0.15 \div 1)I_n$,	step 0.01In
Trip time delay	$t_{I<} = (0.1 \div 90)s$,	step 0.01s

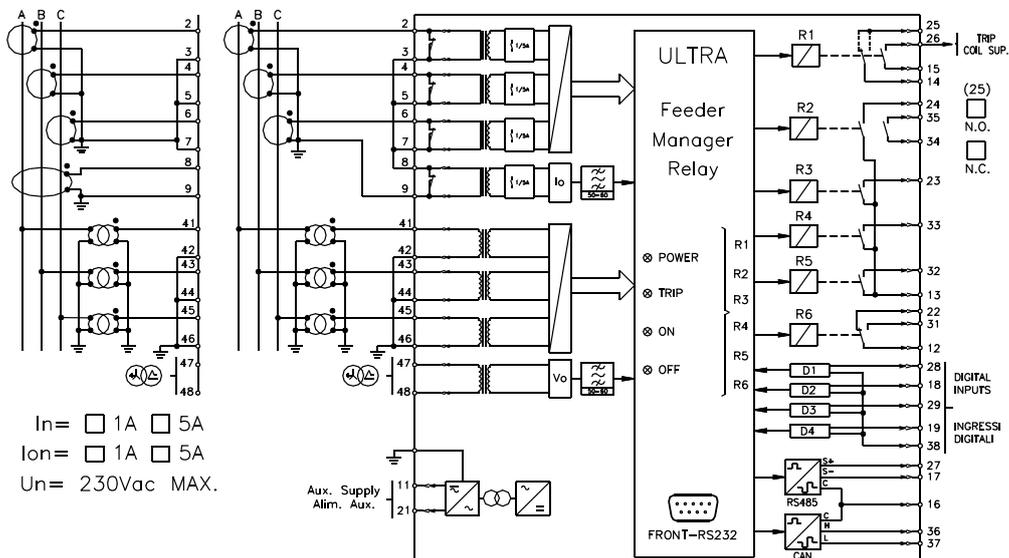
Starting Sequence Control

Function enabling	ON - OFF	
Switch-over (transition) current	$I_{Tr} = (0.1 \div 1)I_{st}$	step 0.01Ist.
Maximum switch-over time delay	$t_{Tr} = (0.5 \div 50)s$.	step 0.1s.

Motor Starts

Setting Range (Min. level for motor ON)	$I_s = (0.05 \div 50) I_n$	step 0.01In
Motor start filter time	$t_{fSt} = (0.02 \div 1)s$	step 0.01s
Motor Starting time	$t_{St} = (10 \div 120)s$	step 0.01s

Connection Diagram



Typical Characteristics

Accuracy at reference value of influencing factors	1% In - 0.1% On	for measure
	2% + to (to=20 ÷ 30ms @ 2xIs)	for times
Rated Current	In = 1 or 5A - On = 1 or 5A	
Current overload	80 In for 1 sec; 4 In continuous	
Burden on current inputs	Phase : 0.01VA at In = 1A; 0.2VA at In = 5A	
	Neutral : 0.01VA at In = 1A ; 0.2VA at In = 5A	
Rated Voltage	Un = 100 ÷ 125V	
Voltage Overload	2Un continuous	
Burden on voltage input	0.1 VA at Un	
Average power supply consumption	<10 VA	
Output Relays	rating 5 A; Vn = 380 V A.C. resistive switching = 1100W (380V max) make= 30 A (peak) 0.5 sec., break = 0.3 A, 110 Vcc, L/R = 40 ms (100.000 op.)	

Order Code - Example

FMR-M	1	2	1	1	1	2
	Power Supply	Phase Rated	Neutral Rated	Configuration	1 st Expansion	2 nd Expansion
		Input Current	Input Current	R1 (14-25)	module	module
	1 = Type 1	1 = 1A	1 = 1A	1 = N.O.	1 = None	1 = None
	2 = Type 2	2 = 5A	2 = 5A	2 = N.C.	2 = UX10-4	2 = UX10-4
					3 = 14DI	3 = 14DI
					4 = 14DO	4 = 14DO

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For further technical information on our products visit www.microelettrica.com

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